



PVD3XDN

Proportional Valve Driver, direct DIN solenoid mount, DIN cable connector

BENEFITS AND FEATURES:

- Versatile digital design
- Large, easy-to-use adjustments and three-digit seven-segment LED display
- Wide range of supply voltage
- Electronic limiting circuit / short circuit proof
- Load can be connected & disconnected live
- Protected against wrong connection
- Energy-efficient PWM circuit, no heat sink is required
- Current sensing maintains output regardless of changes in supply voltage and coil resistance
- Completely sealed even during set-up
- Simple control with analog input
- Thick wall, sturdy housing made of flame retardant plastic UL94-V0
- Mounting: DIN 43650-A/ISO 4400 for solenoid as well as cable connector
- Easy troubleshooting / cable length not an issue



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SPECIFICATIONS:

- Operating voltage: 9 - 35VDC
- Maximum output current: 3A
- Ramp time: 0.0 to 99.5s
- Linearity: 0.5%
- PWM / Dither frequency: 50-500Hz
- Operating temperature: -40° to +75° Celsius
- Input signal: differential +/-10V
- Protection grade: IP67

This product fulfills the essential requirements of
the EMC Directive 2004/108/EC: EN61000-6-1:2005, EN61000-6-3:2006



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SETTINGS AND RANGE:

- HI** High, output current corresponding to the highest input, 0.00 to 3.00 A
- JS** Jog, used to simulate signal, 0.00 to 3.00 A
- LO** Low, output current corresponding to the lowest input, 0.00 to 3.00 A
- UP** Ramp up, time required for the output to increase from LO to HI, 00.0 to 99.5 s
- dn** Ramp down, time required for the output to decrease from HI to LO, 00.0 to 99.5 s
- db** Deadband, output is disabled when command signal is less than this setting, in %
- df** Dither frequency, 050 to 500 Hz
- in** Input signal selection, 0 10 (differential +/-10V)
- di** Display orientation, normal or up-side-down
- SA** Save settings

SET-UP PROCEDURE:

At power up, you may rotate **#** clockwise to read the actual solenoid output current directly in Amps or counterclockwise to read the command input signal in V or mA, corresponding to the input range pre-selected. To enter set-up mode, rotate *****; the display will show the settings sequentially: **HI**, **JS**, **LO**, **UP**, **dn**, **db**, **df**, **in**, **di** and **SA**.

When you reach the setting that you want to modify, rotate **#** up or down to the desired value. To modify another setting, rotate ***** and repeat. The Driver is fully functional during the set-up procedure with any adjustments effective immediately (except the input range selection that becomes effective only after saving). In order to write the new settings in the memory and return to normal mode of operation, rotate ***** until the display shows **SA** and then rotate **#** one full turn. If you do not want to keep the new settings, simply power down without saving.

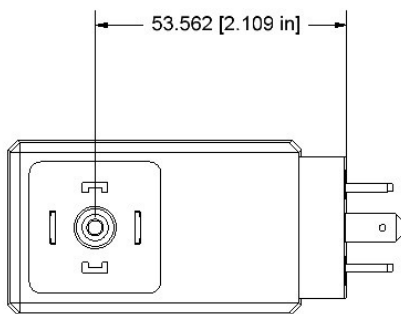
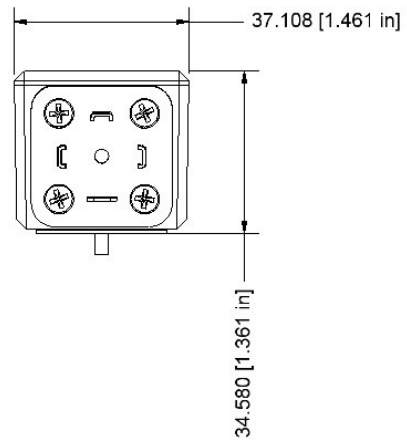
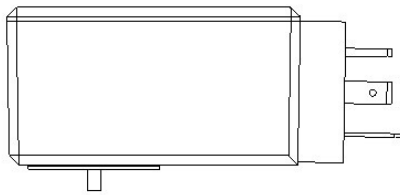
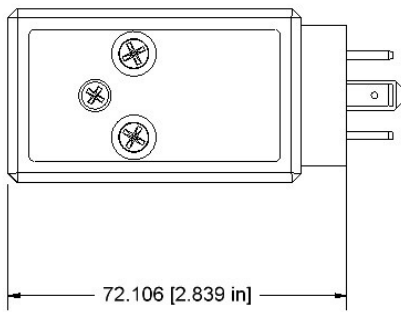
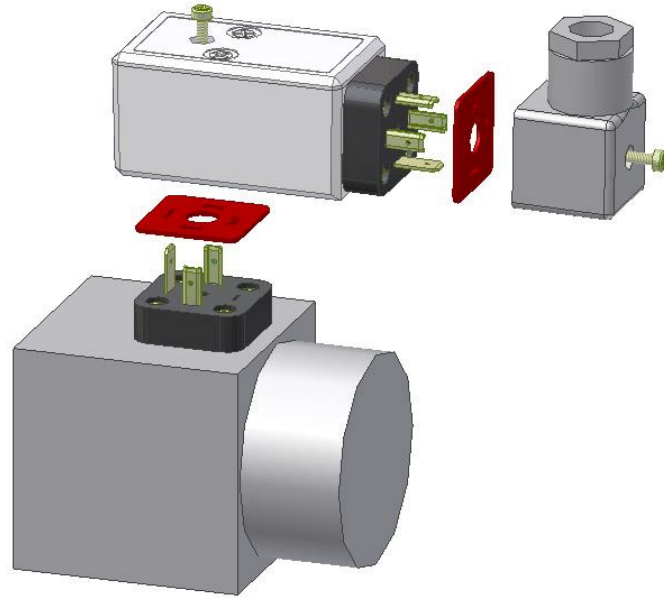
WE RESERVE THE RIGHT TO DISCONTINUE MODELS OR CHANGE SPECIFICATIONS
WITHOUT NOTICE OR INCURRING OBLIGATION



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DIMENSIONS:



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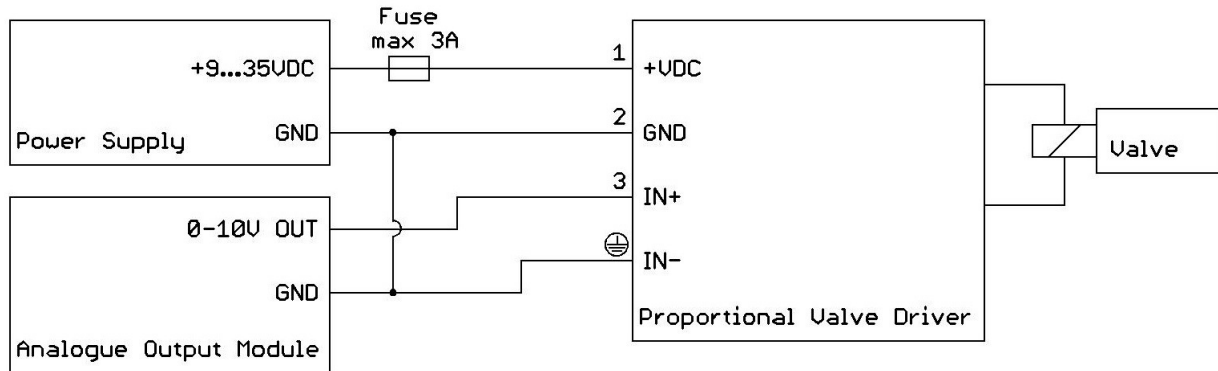


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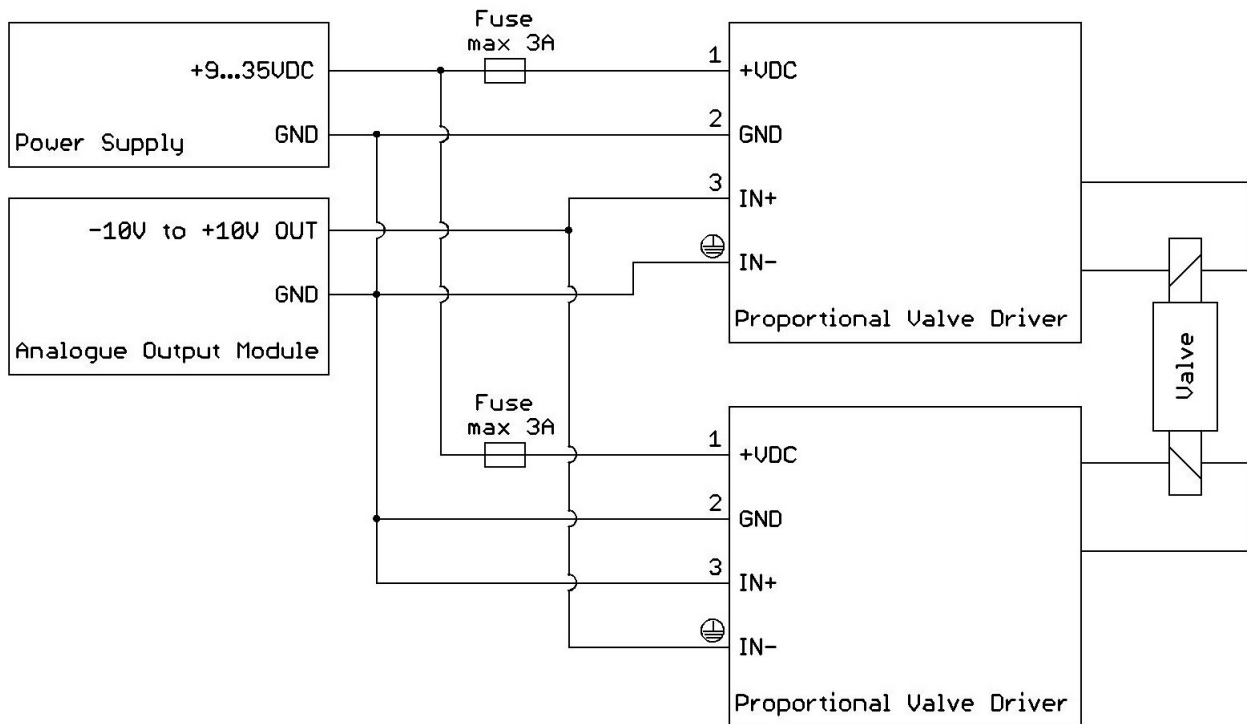
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WIRING DIAGRAMS:

Single solenoid, 0 to +10V command input signal:



Dual solenoid, -10V to +10V command input signal:



NOTE: Do not connect pin \oplus to ground